## List of Topics A Level Mathematics

Торіс	Sub Topics	Topics	
1. Algebraic methods	1.1 Proof by contradiction	2. Functions and graphs	2.1 The modulus function
	1.2 Algebraic functions		2.2 Functions and mappings
	1.3 Partial fractions		2.3 Composite functions
	1.4 Repeated factors		2.4 Inverse functions
	1.5 Algebraic division		2.5 y = $  f(x)  $ and y = f(   x   )
			2.6 Combining transformations
			2.7 Solving modulus problems
3. Sequences and	3.1 Arithmetic sequences	4. Binomial expansion	4.1 Expanding (1 + x) <sup>n</sup>
series	3.2 Arithmetic series		4.2 Expanding (a + bx) <sup>n</sup>
	3.3 Geometric sequences		4.3 Using partial fractions
	3.4 Geometric series		4.4 Transforming functions
	3.5 Sum to infinity		
	3.6 Sigma notation	-	
	3.7 Recurrence relations		
	3.8 Modelling with series	-	
5. Radians	5.1 Radian measure	6. Trigonometric	6.1 Secant, cosecant and
		functions	cotangent
	5.2 Arc length		6.2 Graphs of sec(x), cosec(x) and cot(x)
	5.3 Areas of sector and segments		6.3 Using sec(x), cosec(x), and
	5.4 Solving trigonometric equations		6.4 Trigonometric identities
	5.5 Small angle approximations	-	6.5 Inverse trigonometric
			functions
7. Trigonometry and	7.1 Addition formulae	8. Parametric	8.1 Parametric equations
modelling	7.2 Using the angle addition	equations	8.2 Using trigonometric identities
	7 3 Double-angle formulae		8 3 Curve sketching
	7.4 Solving trigonometric equations	-	8.4 Points of intersection
	7.5 Simplifying a $cos(x) + b sin(x)$	-	8.5 Modelling with parametric
	7.6 Proving trigonometric identities	-	equations
	7.7 Modelling with trigonometric	-	
	functions		
9. Differentiation	9.1 Differentiation sin(x) and cos(x)	10. Numerical methods	10.1 Locating roots
	9.2 Differentiating exponentials and		10.2 Iteration
	logarithms	-	
	9.3 The chain rule		10.3 The Newton-Raphson method
	9.4 The product rule		10.4 Applications to modelling
	9.5 The quotient rule		
	9.6 Differentiating trigonometric	-	
	functions		
	9.7 Parametric differentiation		
	9.8 Implicit differentiation		
	9.9 Using second derivatives		
	9.10 Rates of change		
11. Integration	11.1 Integrating standard functions	12. Vectors	12.1 3D coordinates

11.2 Integrating f(ax + b)	12.2 Vectors in 3D
11.3 Using trigonometric identities	12.3 Solving geometric problems
11.4 Reverse chain rule	12.4 Application to mechanics
11.5 Integration by substitution	
11.6 Integration by parts	
11.7 Partial fractions	
11.8 Finding areas	
11.9 The trapezium rule	
11.10 Solving differential equations	
11.11 Modelling with differential	
equations	
11.12 Integration as the limit of a	
sum	

## A Level Applied Mathematics Topic List

Торіс	Subtopic	Торіс	Subtopic
1. Regression,	1.1 Exponential models	2. Conditional	2.1 Set notation
correlationand		probability	
hypothesis	1.2 Measuring correlation		2.2 Conditional probability
testing	1.3 Hypothesis testing for zero		2.3 Conditional probabilities in
	correlation		Venndiagrams
			2.4 Probability formulae
			2.5 Tree diagrams
3. The normal	3.1 The normal distribution	4. Moments	4.1 Moments
distribution			
	3.2 Finding probabilities for normal		4.2 Resultant moments
	2.2 The inverse normal distribution	-	
	function		
	3.4 The standard normal		4.4 Centre of mass
	distribution		
	3.5 Finding $\mu$ and $\sigma$		4.5 Tilting
	3.6 Approximating a binomial		
	distribution		
	3.7 Hypothesis testing with the		
	normal distribution		
5. Forces and friction	5.1 Resolving forces	6. Projectiles	6.1 Horizontal projection
	5.2 Inclined planes		6.2 Horizontal and vertical
			components
	5.3 Friction		6.3 Projection at any angle
			6.4 Projectile motion formulae
7. Applications of forces	7.1 Static particles	8. Further kinematics	8.1 Vectors in kinematics
	7.2 Modelling with statics		8.2 Vector methods with
			projectiles
	7.3 Friction and static particles		8.3 Variable acceleration in one
			dimension
	7.4 Static rigid bodies		8.4 Differentiating vectors
	7.5 Dynamics and inclined planes		8.5 Integrating vectors
	7.6 Connected particles		